L Number	Hits	Searca Text	DB	Time stamp
1	1	"20040046736" and regions	USPAT;	2004/08/16
		<b>,</b>	US-PGPUB;	12:14
	l		EPO; JPO;	
			DERWENT;	
			IBM TDB	
2	0	"20040046736" and sub-regions	USPĀT;	2004/08/16
			US-PGPUB;	11:35
ļ			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
3	0	"20040046736" and region\$1 and devide	USPAT;	2004/08/16
			US-PGPUB;	11:35
	1		EPO; JPO;	
			DERWENT;	
_			IBM_TDB	
4	0	"20040046736" and region\$1 and divide\$9	USPAT;	2004/08/16
			US-PGPUB;	11:35
			EPO; JPO;	
	ļ l		DERWENT;	
<sub>c</sub>		6 661 010 mm and out mariana	IBM_TDB	2004/09/16
5	)	6,661,918.pn. and sub-regions	USPAT;	2004/08/16
(	(		US-PGPUB;	11:36
	¥		EPO; JPO; DERWENT;	
	<b>(</b>		IBM TDB	
6	0	6,125,198.pn. and sub-regions	USPAT;	2004/08/16
٥	"	6,125,196.pm. and sub-regions	US-PGPUB;	11:37
			EPO; JPO;	11.37
			DERWENT;	
			IBM TDB	
7	1	6,125,198.pn. and regions and divide\$9	USPAT;	2004/08/16
,	_	, c,c,c c,	US-PGPUB;	12:14
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
8	0	6,125,198.pn. and depth	USPAT;	2004/08/16
	ř		US-PGPUB;	12:14
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
9 .	1	"20040046736" and depth	USPAT;	2004/08/16
			US-PGPUB;	12:15
			EPO; JPO;	
			DERWENT;	
10		"20040046736" and depth and coordinate\$1	IBM_TDB	2004/00/16
10	1	20040046736 and depth and coordinate\$1	USPAT;	2004/08/16
			US-PGPUB; EPO; JPO;	12:19
			DERWENT;	
	}		IBM TDB	
11	1	"20040046736" and selected and object	USPAT;	2004/08/16
		and interest	US-PGPUB;	13:02
			EPO; JPO;	
	<u> </u>	,	DERWENT;	
			IBM TDB	
12	1	"20040046736" and selected	USPAT;	2004/08/16
	_		US-PGPUB;	13:02
1			EPO; JPO;	
			DERWENT;	
			IBM_TDB	,
_	584	stereo adj vision	USPAT;	2004/08/13
		·	US-PGPUB,	15:42
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	1

-	203	stered adj vision and interface\$6 and	USPAT;	2004/08/12
		application	US-PGPUB;	09:42
			EPO; JPO;	
			DERWENT;	
_	30	stereo adj vision and interface\$6 and	IBM_TDB USPAT;	2004/08/12
_	30	application adj program and run\$9	US-PGPUB;	09:43
		application adj program and imity	EPO; JPO;	09.43
	İ		DERWENT;	
			IBM TDB	
_	30	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:43
		computer	EPO; JPO;	
			DERWENT;	
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-	26		USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:43
		computer and camera\$1	EPO; JPO;	
			DERWENT;	
	26	stores add wision and intenfaces and	IBM_TDB	2004/09/15
_	26	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/15 16:26
		computer and camera\$1 and first and	EPO; JPO;	10.20
		second	DERWENT;	
		5000114	IBM TDB	
_	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:44
		computer and camera\$1 and first and	EPO; JPO;	<u>'</u>
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1	IBM_TDB	*
-	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:45
		computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and	EPO; JPO; DERWENT;	
		image\$1 and detect\$9	IBM TDB	
_	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
•		application adj program and run\$9 and	US-PGPUB;	09:45
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1	IBM TDB	
<b>–</b>	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:46
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
	1	image\$1 and detect\$9 and object\$1 and	IBM_TDB	
_	8	intersect\$6   stereo adj vision and interface\$6 and	USPAT;	2004/08/12
=	"	application adj program and run\$9 and	US-PGPUB;	09:46
		computer and camera\$1 and first and	EPO; JPO;	02110
	}	second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM TDB	
		intersect\$6 and field\$1 and view\$1	_	
_	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:47
•	1	computer and camera\$1 and first and	EPO; JPO;	,
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and		
_		depth\$1 and range\$1	HEDAM.	2004/09/12
<del>-</del>	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and computer and camera\$1 and first and	US-PGPUB; EPO; JPO;	09:47
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM TDB	
		intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user		
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8 stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6	2004/08/12 09:47
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intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6	
depth\$1 and range\$1 and user and select\$6	
- 8 stereo adj vision and interface\$6 and USPAT;	2004/08/12
application adj program and run\$9 and US-PGPUB;	09:48
computer and camera\$1 and first and EPO; JPO;	
second and arrange\$6 and configurat\$6 and DERWENT;	
image\$1 and detect\$9 and object\$1 and IBM_TDB	
intersect\$6 and field\$1 and view\$1 and	
depth\$1 and range\$1 and user and select\$6	
AND CONTROL\$6	
- 8 stereo adj vision and interface\$6 and USPAT;	2004/08/12
application adj program and run\$9 and US-PGPUB;	09:48
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intersect\$6 and field\$1 and view\$1 and	
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AND CONTROL\$6 and region\$1  O stereo adj vision and interface\$6 and USPAT;	2004/08/12
application adj program and run\$9 and US-PGPUB;	09:49
computer and camera \$1 and first and EPO; JPO;	09.45
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- 0 stereo adj vision and interface\$6 and USPAT;	2004/08/12
application adj program and run\$9 and US-PGPUB;	09:49
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and object and interset\$6 AND CONTROL\$6	
and region\$1	2004/00/12
- 8 stereo adj vision and interface\$6 and USPAT;	2004/08/12
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image\$1 and detect\$9 and object\$1 and IBM_TDB intersect\$6 and field\$1 and view\$1 and	
depth\$1 and range\$1 and user and select\$6	
and object and interest\$6 AND CONTROL\$6	
and region\$1	
- 7 stereo adj vision and interface\$6 and USPAT;	2004/08/12
application adj program and run\$9 and US-PGPUB;	09:51
computer and camera \$1 and first and EPO; JPO;	
second and arrange\$6 and configurat\$6 and DERWENT;	
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intersect\$6 and field\$1 and view\$1 and	
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and object and interest\$6 AND CONTROL\$6	
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and search and point and interest	<u> </u>

-	0	steres adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/12 09:52
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and	DERWENT; IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and	-	
		depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6	]	
		and region\$1 and position\$6 and location		
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_	4	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/12
		computer and camera\$1 and first and	EPO; JPO;	
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	:	intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6		
		and region\$1 and position\$6 and location		
		and search and point and interest and close\$6 and map and position and		
		coordinate\$1 and position and indicator		
-	8	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/12 10:15
		computer and camera\$1 and first and	EPO; JPO;	10.13
		second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and	DERWENT; IBM TDB	
		intersect\$6 and field\$1 and view\$1 and	1511_155	
	:	depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6		
		and region\$1 and position\$6 and location		
-	13	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/13 12:45
		computer and camera\$1 and first and	EPO; JPO;	12.43
		second and arrange\$6	DERWENT; IBM TDB	: •
- *	1	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and computer and camera\$1 and first and	US-PGPUB; EPO; JPO;	10:24
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and	IBM_TDB	
		depth\$1 and range\$1 and user and select\$6		
		and object and interest\$6 AND CONTROL\$6 and region\$1 and sub adj region\$1		
-	1	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and computer and camera\$1 and first and	US-PGPUB; EPO; JPO;	10:24
		second and arrange\$6 and sub adj region\$1	DERWENT;	
_	1	stereo adj vision and interface\$6 and	IBM_TDB USPAT;	2004/08/12
	•	application adj program and run\$9 and	US-PGPUB;	10:25
		computer and camera\$1 and first and second and sub adj region\$1	EPO; JPO; DERWENT;	
			IBM_TDB	
_	3	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	2004/08/12
		computer and camera\$1 and first and	EPO; JPO;	
		second and divide\$9 adj region\$1	DERWENT; IBM TDB	
_	2	"20040046736"	USPAT;	2004/08/16
			US-PGPUB; EPO; JPO;	08:17
			DERWENT;	
	1	<b>I</b> '	IBM_TDB	1

-	1	"2004-046736" and stereo and vision	USPAT; US-PGPUB;	2004/08/12 14:43
			EPO; JPO; DERWENT;	
			IBM_TDB	
-	1	"20040046736" and capture\$6 and image	USPAT;	2004/08/12
			US-PGPUB; EPO; JPO;	15:04
			DERWENT;	
	4		IBM_TDB	2004 (20 (12
-	1	"20040046736" and processing and image	USPAT; US-PGPUB;	2004/08/12 14:59
			EPO; JPO;	
			DERWENT;	
_	1	"20040046736" and processing and image	IBM_TDB USPAT;	2004/08/12
	_	and user	US-PGPUB;	14:59
			EPO; JPO; DERWENT;	
			IBM TDB	
-	1		USPAT;	2004/08/12
		process\$6 and user	US-PGPUB; EPO; JPO;	15:05
			DERWENT;	
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-	1	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision	USPAT; US-PGPUB;	2004/08/12 15:49
		processy's and abor and beered and vision	EPO; JPO;	
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_	0	"20040046736" and capture\$6 and image and	IBM_TDB USPAT;	2004/08/12
		process\$6 and user and stereo and vision	US-PGPUB;	15:50
		and map and coordinate\$1	EPO; JPO;	
			DERWENT; IBM TDB	
-	1	"20040046736" and capture\$6 and image and	USPAT;	2004/08/12
		<pre>process\$6 and user and stereo and vision and coordinate\$1</pre>	US-PGPUB; EPO; JPO;	16:06
		and coordinate;	DERWENT;	
			IBM_TDB	2004/00/12
, <del>-</del>	1	"20040046736" and reference	USPAT; US-PGPUB;	2004/08/12 16:06
			EPO; JPO;	
			DERWENT;	
_	1	"20040046736" and reference and compare\$6	<pre>IBM_TDB USPAT;</pre>	2004/08/13
	_		US-PGPUB;	10:49
			EPO; JPO; DERWENT;	
			IBM_TDB	
-	0		USPAT;	2004/08/12
		reference	US-PGPUB; EPO; JPO;	16:09
			DERWENT;	
_	o	"20040046736" and compare\$6 and	IBM_TDB USPAT;	2004/08/12
-	١	reference adj camera	US-PGPUB;	16:09
			EPO; JPO;	
			DERWENT; IBM TDB	
-	3	6,720,949	USPAT;	2004/08/12
			US-PGPUB;	16:11
			EPO; JPO; DERWENT;	
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-	3	6,720,949.pn.	USPAT;	2004/08/12
			US-PGPUB; EPO; JPO;	16:11
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-	0	6,720,949.pn. and reference adj camera	USPAT;	2004/08/12
			US-PGPUB;	16:11
			EPO; JPO; DERWENT;	
			IBM TDB	
_	1	6,720,949.pn. and two adj cameras	USPAT;	2004/08/12
			US-PGPUB;	16:11
			EPO; JPO;	
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_	o	6,720,949.pn. and two adj cameras and	USPAT;	2004/08/12
		compare\$6 adj images	US-PGPUB;	16:12
			EPO; JPO;	'
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_	ا ه	"20040046736" and two adj cameras and	USPAT;	2004/08/12
		compare\$6 adj images	US-PGPUB;	16:12
ŀ		-	EPO; JPO;	
			DERWENT;	
_	2	5,917,937.pn.	<pre>IBM_TDB USPAT;</pre>	2004/08/12
	_	0,51,,50,.pm	US-PGPUB;	16:13
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		compare\$6 adj images	US-PGPUB;	16:14
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_	0	5 017 027 nn and samoung and samoung	IBM_TDB USPAT;	2004/09/12
-		5,917,937.pn. and cameras and compare\$6 adj images	USPAT; US-PGPUB;	2004/08/12 16:14
			EPO; JPO;	
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		5 Q17 Q37 nn and cameras and compared	IBM_TDB USPAT;	2004/08/12
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	"	5,917,937.pn.	US-PGPUB;	07:06
			EPO; JPO;	
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_	1	5,917,937.pn. and compare\$6	IBM_TDB   USPAT;	2004/08/13
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			EPO; JPO;	
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_	19	stereo adi wision and reference adi	IBM_TDB USPAT;	2004/08/13
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	14	stores and relation and reference and	IBM_TDB	2004/09/12
-	14	stereo adj vision and reference adj camera and feature\$1 and pair\$1	USPAT; US-PGPUB;	2004/08/13 15:35
		dameta and reacuters and parrys	EPO; JPO;	10.00
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-	1	"20040046736" and reference and compare\$6 anD PAIR	USPAT; US-PGPUB;	2004/08/13 12:09
		ain tata	EPO; JPO;	16.03
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-	1	"200 46736" and reference and compares	USPAT; US-PGPUB;	2004/08/13
			EPO; JPO;	
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_	4	stereo adj vision and reference adj	IBM_TDB   USPAT;	2004/08/13
	-	camera and feature\$1 and pair\$1 and	US-PGPUB;	15:32
		filter	EPO; JPO;	
			DERWENT; IBM TDB	
-	o	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and	US-PGPUB;	12:44
		computer and camera \$1 and first and	EPO; JPO;	
		second and arrange\$6 and two adj cameras and compare\$6 adj images	DERWENT; IBM TDB	
-	o	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and	US-PGPUB;	12:44
		computer and camera\$1 and first and second and arrange\$6 and two adj cameras	EPO; JPO; DERWENT;	
		and compare\$6 adj images	IBM TDB	
-	3	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and computer and camera\$1 and first and	US-PGPUB; EPO; JPO;	12:47
		second and arrange\$6 and reference and	DERWENT;	
		compare\$6 anD PAIR and filter\$1 and	IBM_TDB	
		capture\$6 and image and capture\$6 and		
		<pre>image and process\$6 and user and stereo and vision and coordinate\$1</pre>		
-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	12:59
		match and score and rank	EPO; JPO; DERWENT;	
			IBM TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and match and score	US-PGPUB; EPO; JPO;	13:35
		materi and score	DERWENT;	
	_		IBM_TDB	
-	0	stereo adj vision and reference adj' camera and feature\$1 and pair\$1 and	USPAT; US-PGPUB;	2004/08/13 13:35
1		filterand and reference and compare\$6 anD	EPO; JPO;	13.33
		PAIR and filter and calculate and match	DERWENT;	
	1	and score and eliminate "20040046736" and reference and compare\$6	IBM_TDB USPAT;	2004/08/13
	-	anD PAIR and filter and calculate and	US-PGPUB;	13:36
		match and score and eliminate	EPO; JPO;	
			DERWENT;	
-	1	"20040046736" and reference and compare\$6	IBM_TDB USPAT;	2004/08/13
	_	anD PAIR and filter and calculate and	US-PGPUB;	13:42
		match and score and eliminate and	EPO; JPO;	
		feature\$1	DERWENT; IBM TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	14:17
		match and score and eliminate and feature\$1 and threshold	EPO; JPO; DERWENT;	
		TOWNSHIP WING CHILCHIOIG	IBM TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/15
		anD PAIR and filter and calculate and match and score and eliminate and	US-PGPUB; EPO; JPO;	14:32
		feature\$1 and threshold and scene and	DERWENT;	
		coordinate	IBM_TDB	
-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and match and score and eliminate and	US-PGPUB; EPO; JPO;	14:21
		feature\$1 and threshold and scene and	DERWENT;	
		coordinate and divide\$9 and block\$1	IBM_TDB	

0   "2004/0046736" and reference and compares   US-PGPUB;   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22   14:22					
match and score and eliminate and features1 and threshold and scene and coordinate and divides9   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/1	-	0	"20040046736" and reference and compare\$	USPAT;	2004/08/13
features1 and threshold and scene and coordinate and divides9 and parts and filter and calculate and match and score and eliminate and coordinate and (divides9 or splits9) and match and score and eliminate and features1 and threshold and scene and compares6 and parts and threshold and scene and condinate and (divides9 or splits9 or differentiate) and block31   USPAT, USPAT				US-PGPUB;	14:22
1			match and score and eliminate and	EPO; JPO;	
- 0				DERWENT;	
anD PATR and filter and calculate and match and score and eliminate and coordinate and (divides9 or splits9) and block\$1  - 0 "20040046736" and reference and compare\$6 and PATR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 oR DIFFERENTIALB) and block\$1  - 0 "20040046736" and reference and compare\$6 and PATR and filter and calculate and match and score and eliminate and coordinate and (divide\$9 or split\$9 oR DIFFERENTIALB) and block\$1  - 0 "20040046736" and reference and compare\$6 and PATR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1  - 0 \$5,159,159.pn. and horizontal and synch9  - 0 \$5,159,159.pn. and horizontal and synch99  - 0 \$5,159,159.pn. and horizonta	ļ			_	
### Task and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9) and block\$1  - 00 "20040046736" and reference and compare\$6 and FATR and filter and calculate and match and score and eliminate and coordinate and (divide\$9 or split\$9 OR DERWENT; BM_TDB and block\$1  - 00 "20040046736" and reference and compare\$6 and FATR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 OR differentiate) and block\$1  - 1 "20040046736" and reference and compare\$6 and FATR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and lock\$1  - 1 \$5,159,159.pn and horizontal SPAT; US-PGPUB; EPO, JPO; DERWENT; BM_TDB SPAT; US-PGPUB; BPO; JPO; DERWENT; BM_	-	0			
feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9) and hlock\$1				•	14:22
Coordinate and (divide\$9 or split\$9) and   IBM_TDB					
Diock31			· · · · · · · · · · · · · · · · · · ·		
0   "20040046736" and reference and compares   0   SPAT;   and PAIR and filter and calculate and match and score and eliminate and features   and threshold and scene and coordinate and (divide\$9 or split\$9 OR DIFFRENTIALE) and block\$1   IBM_TDB   14:23   2004/08/13   18:26   2004/08/13   18:27   2004/08/13   18:27   2004/08/13   18:28   2004/08/13   18:28   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004/08/13   18:29   2004				IBM_TDB	1
and PAIR and filter and calculate and match and score and eliminate and coordinate and features! and threshold and scene and coordinate and match and score and eliminate and match and score and eliminate and match and score and eliminate and coordinate and features! and threshold and scene and coordinate and match and score and eliminate and coordinate and features! and threshold and scene and coordinate and match and score and eliminate and provided features! and threshold and scene and coordinate and holock;!  - 1 5,159,159,pn and horizontal USPAT; DEWENT; DE				HCDAM.	2004/09/12
### Match and score and eliminate and features! and threshold and scene and cordinate and (divide59 or split59 OR DIFFRENTILE) and blocks!  - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and features! and threshold and scene and compare\$6 and PAIR and filter and calculate and match and score and eliminate and factorial and blocks!  - 1 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and features! and threshold and scene and coordinate and blocks! and pattern and luminance and pixels  - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and features! and threshold and scene and coordinate and pixels - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and features! and threshold and scene and coordinate and block\$1 and puttern and features! and threshold and scene and coordinate and block\$1 and puttern and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features! and threshold and scene and coordinate and block\$1 and luminance and features!	-	١			
features1 and threshold and scene and coordinate and (divides9 or splits9 OR DIFFERENTIALE) and block\$1					11.22
Coordinate and (divide99 or split\$9 OR   IBM_TDB   DIFFERENTIALE) and block\$1   20040046736" and reference and compare\$6   and PARR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide99 or split\$9 or differentiate) and block\$1   1"20040046736" and reference and compare\$6   and PARR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1   SpAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JP					
DIFFERENTIALE) and block\$1  0 "20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and climinate and feature\$1 and threshold and scene and coordinate and match and score and climinate and match and score and climinate and feature\$1 and threshold and scene and coordinate and block\$1  - 0 5,159,159.pn  1 5,159,159.pn  1 5,159,159.pn  2 0 5,159,159.pn  2 0 5,159,159.pn  3 5,159,159.pn  4 0 5,159,159.pn  5 1 5,159,159.pn  2 0 5,159,159.pn  3 1 5,159,159.pn  4 1 5,159,159.pn  5 2 004/08/13 15:02  1 1 5,159,159.pn  4 2 0 5,159,159.pn  5 3 1 5,159,159.pn  5 3 1 5,159,159.pn  6 2 1 5,159,159.pn  6 3 1 5,159,159.pn  7 0 5 1 5,159,159.pn  8 2 1 1 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			·		
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match and score and eliminate and feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 or differentiate) and block\$1	-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
Feature\$1 and threshold and scene and coordinate and (divide\$9 or split\$9 or differentiate) and block\$1					14:23
Coordinate and (divide\$9 or split\$9 or differentiate) and block\$1					
1   20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and block\$1   2004/08/13   15:02   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13   2004/08/13			•		
1				TRW_IDR	
anD PAIR and filter and calculate and match and score and liminate and feature\$1 and threshold and scene and coordinate and block\$1   S,159,159.pn   DERWENT; ISM TDB USPAT; US-PGPUB; EPO, JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO, JPO; DER	1_	1		ווקסמיי -	2004/08/13
match and score and eliminate and features and toordinate and block\$1					
feature\$1 and threshold and scene and coordinate and block\$1	1			i i	
- 0 5,159,159.pn and horizontal USPAT; US-PGPUB; PDO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; PDO; JPO; DERWENT					
S-PGPUB;   EPO; JPO; DERWENT;   IBM TDB   USPAT; US-PGPUB;   EPO; JPO; DERWENT;   IBM TDB   USPAT; US-PGPUB;   EPO; JPO; DERWENT;   IBM TDB   USPAT; US-PGPUB;   EPO; JPO; DERWENT;   IBM TDB   USPAT;					_
EPO: JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; END TDB ERWENT; EPO; JPO; DERWENT; EPO; JP	-	0	5,159,159.pn	·	
DERWENT; IBM TDB					14:29
1   5,159,159.pn. and horizontal   USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO;					
1   5,159,159.pn. and horizontal   USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PCPUB; EPO; JPO; DERWENT; IBM TDB USPAT; USPAT; USPAT; USPCPUB; EPO; JPO; DERWENT; IBM TDB USPAT; USPCPUB; EPO; JPO; DERWENT; IBM TDB USPAT;			,		
US-PGPUB; EPO; JPO; DERWENT; IBM TDB US-PGPUB; E	_	1	5.159 159.pp. and horizontal	_	2004/08/13
EPO; JPO; DERWENT; IBM TDB USPĀT; US-PGPUB; EPO; JPO; DERWENT; ISM TDB		1	o, 105, 105. pm. and northonour	· ·	
5,159,159.pn. and horizontal and synch  1 5,159,159.pn. and horizontal  1 5,159,159.pn. and horizontal  2004/08/13 14:29 EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB				· ·	
5,159,159.pn. and horizontal and synch  5,159,159.pn. and horizontal and synch;  105-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS:02 EPO; JPO; DERWENT; ISM_TDB USPAT; US-PGPUB; IS:03 EPO; JPO; DERWENT; ISM_TDB IS:03 EPO; JPO; DERWENT; IBM_TDB IS:03 EPO; JPO; DERWENT; IBM_TDB IS:03 EPO; JPO; DERWENT; ISM_TDB IS:03 EPO; JPO; DERWENT; ISM_TDB IS:04 IS:04/08/13 IS:05				DERWENT;	
US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWEN	-		,		
EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB US-PGPUB; IS:02  - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and luminance and pixels  - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and luminance IBM TDB US-PGPUB; IS:03  - 0 "20040046736" and reference and compare\$6 and PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and luminance IBM TDB US-PGPUB; IS:03	<b>-</b>	0	5,159,159.pn. and horizontal and synch		
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS-02 IS-04/08/13 US-PGPUB; IS-02 IS-04/08/13 IS-02 IS-04/08/13 IS-02 IS-04/08/13 IS-03 IS					14:29
TIBM_TDB USPAT;					
- 0 5,159,159.pn. and horizontal and synch\$9  - 1 5,159,159.pn. and horizontal Synch\$9  - 1 5,159,159.pn. and horizontal Synch\$9  - 1 5,159,159.pn. and horizontal Synch\$9  - 20040046736" and horizontal Synch\$9  - 20040046736" and reference and compare\$6					
US-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB UMINANCE and block\$1 and pattern and luminance and pixels  - 0 "20040046736" and reference and compare\$6 anD PAIR and filter and calculate and pixels and pixels us-PGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; EPO; JPO; DERWENT; EPO; JPO; DERWENT; EPO; JPO; DERWENT; EP	-	o	5,159,159.pn. and horizontal and synch\$9		2004/08/13
DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB US-PGPUB; EPO; JPO; DERWENT; ISM_TDB US-PGPUB; IS:03	1		· · · · · · · · · · · · · · · · · · ·	·	
- 1 5,159,159.pn. and horizontal					
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-	1	"20040046736" and pixel\$1	USPAT;	2004/08/13
			US-PGPUB;	15:40
			EPO; JPO;	
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-	3		USPAT;	2004/08/13
		camera and feature\$1 and pair\$1 and	US-PGPUB;	15:38
		filter and pixel\$1	EPO; JPO;	
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<b>!</b> _	8	stereo adj vision and refereńce adj	USPAT;	2004/08/13
		camera and feature\$1 and pair\$1 and	US-PGPUB;	15:37
		matrix and pixel\$1	EPO; JPO;	13.37
		macran min principa	DERWENT;	
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-	l 0	stereo adj vision and reference adj	USPAT;	2004/08/13
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	1	and "8x8"	US-PGPUB;	15:38
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-	12		USPAT;	2004/08/13
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_	241	stereo adj vision and display and pixel\$1	USPAT;	2004/08/13
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_	0	stereo adj vision and display and pixel\$1 and active adj matrix and "8x8"	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2004/08/13 15:45
-	9	stereo adj vision and display and pixel\$1	DERWENT; IBM_TDB USPAT;	2004/08/13
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-	1	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:05
_	0	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare and	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:33
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		pairs and disparity and select\$9 and	EPO; JPO;	
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_	1	"20040046736" and head\$1 and smooth\$6 and	<pre>IBM_TDB USPAT;</pre>	2004/08/14
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_		image\$1 stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest and close\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 13:50
_	1		USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:33
-	0	6,125,198.pn. and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:18
-	0	"20040046736" and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 14:17
_	0	"20040046736" and mapp\$6	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 14:18
-	0	"20040046736" and map	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 14:18
_	0	6,125,198.pn. and map	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 16:26
-	1	"20040046736" and stereo adj image and stereo adj camera	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 14:58
-	0	"20040046736" and x-axis	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:58

-	1	"200-0046736" and x and axis	USPAT;	2004/08/15
			US-PGPUB;	15:00
			EPO; JPO;	
			DERWENT;	
		#2004004C72C# and # and arris and hand01	IBM_TDB	2004/09/15
_	1	"20040046736" and x and axis and hand\$1	USPAT;	2004/08/15 15:33
			US-PGPUB; EPO; JPO;	15:33
			DERWENT;	
			IBM TDB	
	1	"20040046736" and X and axis and Z	USPAT;	2004/08/15
	_		US-PGPUB;	15:34
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	"20040046736" and X and axis and Z and	USPAT;	2004/08/15
		depth	US-PGPUB;	15:35
			EPO; JPO;	
			DERWENT;	
	1	"20040046736" and (storage or storse) and	IBM_TDB USPAT;	2004/08/15
-	1	"20040046736" and (storage or stor\$6) and orient\$6 and posit\$6 and coordinate\$6	US-PGPUB;	16:25
		orrened and besteds and contamareds	EPO; JPO;	10.20
			DERWENT;	
			IBM TDB	
-	0	"20040046736" and avatar	USPAT;	2004/08/15
			US-PGPUB;	16:29
			EPO; JPO;	
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-	0	6,125,198.pn. and avatar	USPAT;	2004/08/15
			US-PGPUB;	16:26
			EPO; JPO; DERWENT;	
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_	0	6,661,918.pn. and avatar	USPAT;	2004/08/15
		o, ooi, sio.pii. unu uvuoui	US-PGPUB;	16:33
			EPO; JPO;	
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			IBM_TDB	
-	2	stereo adj vision and interface\$6 and	USPAT;	2004/08/15
		application adj program and run\$9 and	US-PGPUB;	16:27
		computer and camera\$1 and first and	EPO; JPO;	
		second and avatar	DERWENT; IBM TDB	
_	ا ر	stereo adj vision and interface\$6 and	USPAT;	2004/08/15
		application adj program and run\$9 and	US-PGPUB;	16:28
		computer and camera\$1 and avatar	EPO; JPO;	
		-	DERWENT;	
-			IBM_TDB	
-	1	stereo adj vision and indicator\$1 and	USPAT;	2004/08/15
		avatar	US-PGPUB;	16:28
			EPO; JPO;	
			DERWENT;	
_	8	stereo adj vision and avatar	<pre>IBM_TDB USPAT;</pre>	2004/08/15
		Secret and vision and availat	US-PGPUB;	16:36
1	]		EPO; JPO;	
1	]		DERWENT;	
1	[		IBM TDB	
-	1	"20040046736" and animation	USPAT;	2004/08/15
1			US-PGPUB;	16:30
1	,		EPO; JPO;	
			DERWENT;	
			IBM_TDB	0004/00/05
-	0	"20040046736" and animation and facial	USPAT;	2004/08/15
		and sens\$6	US-PGPUB;	16:30
		•	EPO; JPO;	
1			DERWENT; IBM TDB	
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-	1	"200-046736" and animation and face and sens\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 16:30
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_	0	6,661,918.pn. and animation	USPAT; US-PGPUB; EPO; JPO;	2004/08/15 16:33
			DERWENT; IBM TDB	
-	0	6,661,918.pn. and animation	USPAT; US-PGPUB;	2004/08/15 16:33
			EPO; JPO; DERWENT;	10.33
-	8	stereo adj vision and avatar and indicat\$6	IBM_TDB USPAT; US-PGPUB;	2004/08/15 16:38
			EPO; JPO; DERWENT;	
_	2	1	IBM_TDB USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and interface\$6 and application adj program	US-PGPUB; EPO; JPO;	16:39
		and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and	DERWENT; IBM_TDB	
		object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user		
	7	and select\$6 AND CONTROL\$6 and region\$1 stereo adj vision and avatar and	USPAT;	2004/08/15
	,	indicat\$6 and stereo adj vision and interface\$6	US-PGPUB; EPO; JPO; DERWENT;	16:39
_	2		IBM_TDB USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and interface\$6 and application adj program and run\$9 and computer	US-PGPUB; EPO; JPO; DERWENT;	16:39
_	3	stereo adj vision and avatar and	<pre>IBM_TDB USPAT;</pre>	2004/08/15
		indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and	US-PGPUB; EPO; JPO;	16:43
		first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and	DERWENT; IBM_TDB	
		view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1		
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and	USPAT; US-PGPUB;	2004/08/15 16:41
		interface\$6 and computer and camera\$1 and first and second and arrange\$6 and	EPO; JPO; DERWENT;	10.41
		configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and	IBM_TDB	
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-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and	USPAT; US-PGPUB;	2004/08/15 16:41
		interface\$6 and computer and camera\$1 and first and second and arrange\$6 and	EPO; JPO; DERWENT;	10.31
		configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and	IBM_TDB	
		view\$1 and depth\$1 and user and select\$6 AND CONTROL\$6		
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and	USPAT; US-PGPUB;	2004/08/15 16:42
		interface\$6 and computer and camera\$1 and first and second and arrange\$6 and	EPO; JPO; DERWENT;	
		configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and	IBM_TDB	
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- 3 stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and user and select\$6 AND CONTROL\$6  - 3 stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and EPO; JPO;	
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- 3 stereo adj vision and avatar and indicat\$6 and stereo adj vision and USPAT; 2004 16:4 interface\$6 and computer and camera\$1 and EPO; JPO;	
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interface\$6 and computer and camera\$1 and EPO; JPO;	
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and detect\$9 and object\$1 and user and IBM_TDB	
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	/08/15
indicat\$6 and stereo adj vision and US-PGPUB; 16:4	3
interface\$6 and computer and camera\$1 and EPO; JPO; image\$1 and detect\$9 and object\$1 and DERWENT;	
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and view\$1 and depth\$1 and range\$1 and	
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indicat\$6 and stereo adj vision and US-PGPUB; 16:4	
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- 7 stereo adj vision and avatar and USPAT; 2004	/08/15
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interface\$6 and computer and camera\$1 and EPO; JPO;	
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and object\$1 and field\$1 and view\$1 and IBM_TDB	
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-	6	stell adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/16 06:47
		and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	IBM_TDB	
-	6	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:57
-	2		USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 07:43
-	1	"20010033675" and map	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16
	6	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 07:44
-	2	"20040046736" and mouse	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 08:17
-	1	"20010033675" and virtual	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 08:48
-	0	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and position and corresponding and hand and object and selected and velocity and function and applied and avatar and roam and virtual and	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16

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	1	stek adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and neutral and hand and object and selected and velocity and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:01
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and hand and object and selected and velocity and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02
-	1	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02

		1	stells adj vision and avatar and stereo adj vision and interface\$6 and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:02
-	-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-		1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and detect\$9 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-		1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and selected and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-		1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and avatar and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
-	•	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:03
		1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 and coordinate\$1 and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:04
-		1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05

-	1 stell adj vision and avatar and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and	USPAT; 2004/08/16 US-PGPUB; 09:05 EPO; JPO; DERWENT;
_	environment and application and program  stereo adj vision and avatar and object\$1 and user and virtual and hands and velocity and roam and virtual and	USPAT; 2004/08/16 US-PGPUB; EPO; JPO; 2004/08/16
-	environment and application and program  stereo adj vision and avatar and virtual and hands and velocity and roam and virtual and environment and application and program	DERWENT; IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:05 EPO; JPO; DERWENT;
-	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment and application and program	IBM_TDB
-	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment	IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:06 EPO; JPO; DERWENT;
-	stereo adj vision and avatar and virtual and velocity and roam and environment	IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:06 EPO; JPO; DERWENT;
-	4 avatar and virtual and velocity and roam and environment	IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:19 EPO; JPO; DERWENT;
-	avatar and virtual and velocity and roam and environment and hand	IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:20 EPO; JPO; DERWENT;
-	avatar and virtual and velocity and roam and environment and hand\$1 and stereo adj vision	IBM_TDB USPAT; 2004/08/16 US-PGPUB; 09:20 EPO; JPO; DERWENT; IBM TDB
-	avatar and virtual and velocity and roam and environment and hand\$1 and interface\$6 and computer and camera\$1	USPAT; 2004/08/16 US-PGPUB; 09:21 EPO; JPO; DERWENT; IBM TDB
-	2 avatar and virtual and velocity and roam and environment and hand\$1 and computer and camera\$1	USPAT; 2004/08/16 US-PGPUB; D9:21 EPO; JPO; DERWENT; IBM TDB
-	avatar and virtual and velocity and roam and environment and hand\$1 and computer	USPAT; 2004/08/16 US-PGPUB; 09:21 EPO; JPO; DERWENT; IBM TDB

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	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and neutral and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16
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_	1	6088035.pn. and selected	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 09:51
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L	Hits	Search Text	DB	Time stamp
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1	2	6,125,198.pn.	US-PGPUB;	09:44
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2	49	6,125,198.pn. threshold and calculating	USPAT;	2004/08/14
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13	o	6,125,198.pn. and threshold and	USPAT;	2004/08/14
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16	1	6,125,198.pn. and threshold and	USPĀT;	2004/08/14
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17	1	6,125,198.pn. and threshold and	USPAT;	2004/08/14
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20	0	6,125,198.pn. and threshold and	USPAT;	2004/08/14
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22	1		USPAT;	2004/08/14
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23	0 !	6,125,198.pn. and threshold and	<pre>IBM_TDB USPAT;</pre>	2004/08/14
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24	1		USPAT;	2004/08/14
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